



Theoretical Limits and Practical Approximations

Zhe Zeng*
University of California. Los Angeles

Antonio Vergari University of California, Los Angeles Paolo Morettin* University of Trento, Italy

Guy Van den Broeck University of California, Los Angeles

Fanqi Yan* University of Texas at Austin





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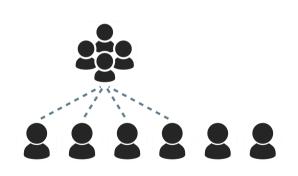


Example: Skill matching system

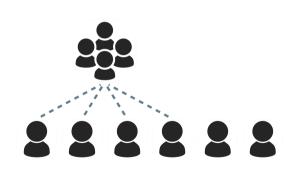
Each *player* has a certain skill continuous variables



$$0 \le X_{P_i} \le 10$$
for $i = 1, \dots, N$

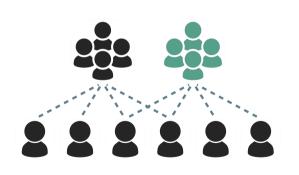


- $0 \le X_{P_i} \le 10$ for $i = 1, \dots, N$
- Players can form **teams**⇒ complex constraints

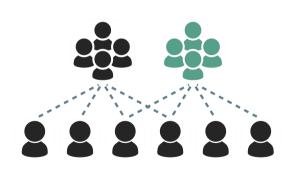


$$0 \le X_{P_i} \le 10$$
 for $i = 1, \dots, N$

$$\mid X_{T_j} - X_{P_i} \mid < 1$$
 for $j = 1, \ldots, M, i = 1, \ldots, |T_j|$

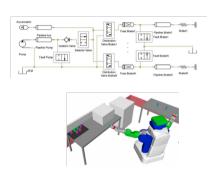


- $0 \le X_{P_i} \le 10$ for $i = 1, \dots, N$
- $\mid X_{T_j} X_{P_i} \mid < 1$ for $j = 1, \dots, M, i = 1, \dots, |T_j|$
- Good teams form a **squad**⇒ discrete variables



- $0 \le X_{P_i} \le 10$ for $i = 1, \dots, N$
- $\mid X_{T_j} X_{P_i} \mid < 1$ for $j = 1, \ldots, M, i = 1, \ldots, |T_j|$
- $B_{S_j} \Rightarrow X_{T_j} > 2$ for $j = 1, \dots, M, i = 1$

Continuous + discrete + constraints = SMT



Satisfiability Modulo Theories of linear arithmetic over the reals (SMT(\mathcal{LRA})) delivers all the ingredients by design!

Widely used as a representation language for *robotics*, *verification* and *planning* [Barrett et al. 2010]

Continuous + discrete + constraints = ?

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Generative adversarial networks (GANs) [Goodfellow et al. 2014] Variational Autoencoders (VAEs) [Kingma et al. 2013]

Hybrid Bayesian Netowrks (HBNs) [Heckerman et al. 1995; Shenoy et al. 2011] Mixed Probabilistic Graphical Models (MPGMs) [Yang et al. 2014]

Tractable Probabilistic Circuits (PCs) [Molina et al. 2018; Vergari et al. 2019]

Continuous + discrete + constraints = ?

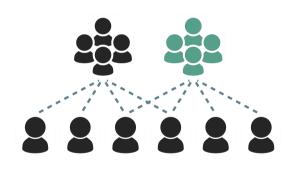
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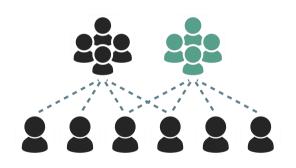
$$\mid X_{T_j} - X_{P_i} \mid < 1$$
 for $j = 1, \ldots, M, i = 1, \ldots, |T_j|$

$$B_{S_j} \Rightarrow X_{T_j} > 2$$
 for $j = 1, \dots, M, i = 1$

$$\Delta = \bigwedge_{i} 0 \le X_{P_i} \le 10 \bigwedge_{j} \bigwedge_{i \in T_j} |X_{T_j} - X_{P_i}| < 1 \bigwedge_{j} (B_{S_j} \Rightarrow X_{T_j} > 2)$$

a single CNF SMT(\mathcal{LRA}) formula Δ ...

Continuous + discrete + constraints = SMT



"What is the probability of team T_1 outperforming team T_2 , if T_1 is a squad but T_2 is not?"

SMT + weights

$$\bigwedge_{i} 0 \leq X_{P_{i}} \leq 10$$

$$\bigwedge_{j} \bigwedge_{i \in T_{j}} |X_{T_{j}} - X_{P_{i}}| < 1$$

$$\bigwedge_{j} (B_{S_{j}} \Rightarrow X_{T_{j}} > 2)$$

$$\downarrow^{w(X_{P_{i}}), \text{ if } 0 \leq X_{P_{i}} \leq 10$$

$$w(X_{T_{j}}, X_{P_{i}}), \text{ if } |X_{T_{j}} - X_{P_{i}}| < 1$$

$$w(B_{S_{j}}, X_{T_{j}}), \text{ if } B_{S_{j}} \Rightarrow X_{T_{j}} > 2$$

SMT formula Δ

weight functions $\,\mathcal{W}\,$

SMT + weights = Weighted Model Integration

$$\bigwedge_{i} 0 \le X_{P_{i}} \le 10$$

$$\bigwedge_{j} \bigwedge_{i \in T_{j}} |X_{T_{j}} - X_{P_{i}}| < 1$$

$$\bigwedge_{j} (B_{S_{j}} \Rightarrow X_{T_{j}} > 2)$$

complex support

densities

(unnormalized)

 $\mathsf{Pr}_{\Delta}(\mathbf{X}, \mathbf{B})$

SMT + densities = Weighted Model Integration

Given an SMT(\mathcal{LRA}) formula Δ over continuous vars $\mathbf X$ and discrete ones $\mathbf B$, and weight function $\mathcal W$, the **weighted model integral** (WMI) is

$$\mathsf{WMI}(\Delta, \mathcal{W}; \mathbf{X}, \mathbf{B}) \triangleq \sum_{\boldsymbol{b} \in \mathbb{R}^{|\mathbf{B}|}} \int_{(\mathbf{x}, \boldsymbol{b}) \models \Delta} w(\mathbf{x}, \boldsymbol{b}) \, d\mathbf{x}.$$



Given an SMT(\mathcal{LRA}) formula Δ over continuous vars $\mathbf X$ and discrete ones $\mathbf B$, and weight function $\mathcal W$, the **weighted model integral** (WMI) is

$$\mathsf{WMI}(\Delta, \mathcal{W}; \mathbf{X}, \mathbf{B}) \triangleq \sum_{\boldsymbol{b} \in \mathbb{B}^{|\mathbf{B}|}} \int_{(\mathbf{x}, \boldsymbol{b}) \models \Delta} w(\mathbf{x}, \boldsymbol{b}) \, d\mathbf{x}.$$

 \implies integrating the **densities** of the **feasible regions** of Δ !

i.e., computing the *partition function* of the unnormalized distribution Pr_{Δ}



"What is the probability of team T_1 outperforming team T_2 , if T_1 is a squad but T_2 is not?"



Advanced probabilistic reasoning

$$\Phi_S: (B_{S_1}=1 \wedge B_{S_2}=0) \implies T_1 \text{ is a squad}, \ T_2 \text{ is not}$$
 $\Phi_T: (X_{T_1}>X_{T_2}) \implies T_1 \text{ outperforms } T_2$



Advanced probabilistic reasoning

$$\Phi_S: (B_{S_1}=1 \wedge B_{S_2}=0) \implies T_1 \text{ is a squad}, \ T_2 \text{ is not}$$

$$\Phi_T: (X_{T_1}>X_{T_2}) \implies T_1 \text{ outperforms } T_2$$

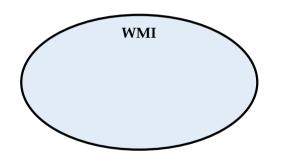
$$\mathsf{Pr}_{\Delta}(\Phi_T \mid \Phi_S) = \frac{\mathsf{WMI}(\Delta \land \Phi_T \land \Phi_S, \mathcal{W})}{\mathsf{WMI}(\Delta \land \Phi_S, \mathcal{W})} = \frac{4,206}{7,225} \approx 58.22\%$$

conditional probabilities as a ratio of two weighted model integrals

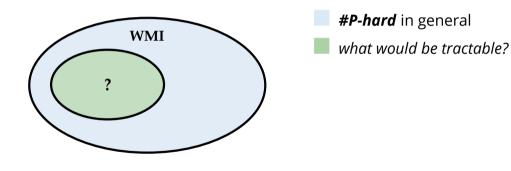
12/20

Why is building inference algorithms for hybrid domains difficult?





#**P-hard** in general



Primal Graph

Discrete Graphical Models

$$\bigwedge_{i=1,2} (X_i \Rightarrow X_{i+1})$$

WMI models

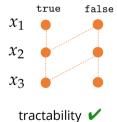
$$\bigwedge_{i=1,2} (X_i \Rightarrow X_{i+1}) \qquad \bigwedge_{i=1,2} \{ (X_i - 0.1 \le X_{i+1} \le X_i + 0.1) \\ \vee (X_i + 0.9 \le X_{i+1} \le X_i + 1.1) \}$$

Primal Graph



Tree Primal Graph

Discrete Graphical Models



WMI models

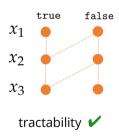
?

Primal Graph

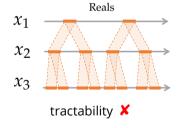


Tree Primal Graph

Discrete Graphical Models

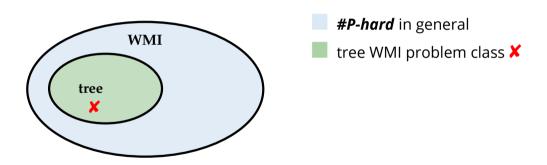


WMI models

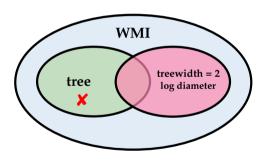


Primal Graph

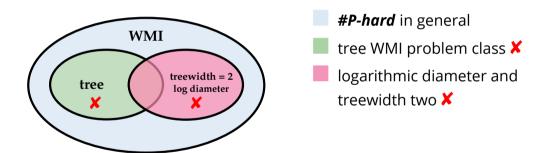




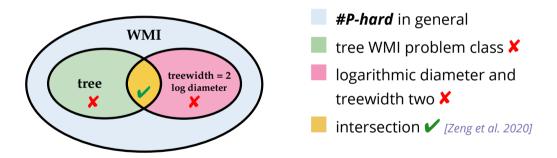
WMI Inference on tree-shaped primal graphs with unbounded-diameter is #P-hard!



- #**P-hard** in general
- tree WMI problem class X
- logarithmic diameter and treewidth two?



WMI inference on primal graphs with bounded-diameter but treewidth two is #P-hard!

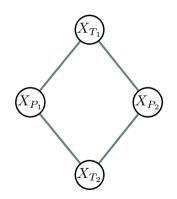


...but how can we perform inference on general WMI problems?



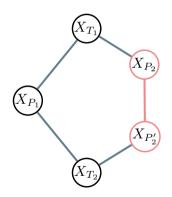


Approximate WMI Inference



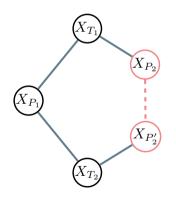
Given a WMI problem with *loopy primal graph*

ReColn



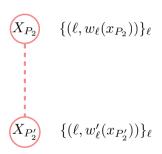
- Given a WMI problem with *loopy primal graph*
- **Re**lax it by adding **copies** of literals

ReColn



- Given a WMI problem with *loopy primal graph*
- Relax it by adding copies of literals, then removing equality constraints
 - removing dependencies, breaking loops





- Given a WMI problem with *loopy primal graph*
- **Re**lax it by adding **copies** of literals, then removing equality constraints
- **Compensate for the removed dependencies,** by introducing certain literals and weights

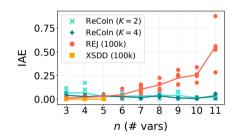


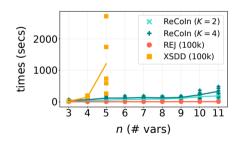
$$w_{\ell} \leftarrow f(\mathsf{Pr}_{\Delta}(\ell); w')$$

$$w'_{\ell} \leftarrow f(\mathsf{Pr}_{\Delta}(\ell); w)$$

- Given a WMI problem with *loopy primal graph*
- Relax it by adding copies of literals, then removing equality constraints
- **Co**mpensate for the removed dependencies, by introducing certain literals and weights
- optimize compensating weights iteratively by solving a series of **exact In**tegration problems

Experiments





⇒ ReColn scales better to larger WMI problems while still delivering accurate approximations

Real-world data is *noisy*...

Real-world data is *noisy*, *complex*...

Real-world data is *noisy*, *complex* and *mixed continuous-discrete*...

Real-world data is **noisy**, **complex** and **mixed continuous-discrete**... **The WMI framework** is very appealing for probabilistic inference in the real-world!

Real-world data is *noisy*, *complex* and *mixed continuous-discrete*... *The WMI framework* is very appealing for probabilistic inference in the real-world! Efficient approximations are not only useful, but *needed*

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⇒ ReCoIn delivers fast approximate inference

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⇒ ReCoIn delivers fast approximate inference

Next

Application to program verification, probabilistic (logic) programming, ...

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⇒ ReCoIn delivers fast approximate inference

Next

Application to program verification, probabilistic (logic) programming, ...

Code

github.com/UCLA-StarAI/recoin

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